



Address Telephone Eax E-Mail Project Person responsible Description of application Person responsible Description of application Project Requirement/number of pieces Requirement per year/potential Preferred delivery date Alignment errors possible Mass moment of inertia [kgm²] Alignment errors possible Requirement [Nm] Preferred delivery date Mass moment of inertia [kgm²] Alignment errors possible Requirement [Nm] Preferred delivery date Required torque [Nm] Holding torque [Nm] Leverage length [mm] Mass [Kg] Rotation speed [*Sace] Positioning accuracy [?] Cycle frequency [rotations/time] Loading changes Mounting position horizontal vertical Normal How rate [ttr/Min] Prejourn-based Switherk How rate [ttr/Min] Prejourn-based Switherk How rate [ttr/Min] Prejour	Company								
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Position request Type [inductive, rotary encoder, etc.]	Desition request		⊔ Angular	adjustment	L Camsna	11			
	Torque transmission via								
Torque transmission via		oline shaft 🛛 F	lange 🗆 Ot	hers					
Torque transmission via □ Pivot shaft □ Hollow shaft □ Spline shaft □ Flange □ Others			J						
Torque transmission via	Spec. requirements for weight/dimensi	ons							
	(Please include sketch or drawing)								
Pivot shaft Hollow shaft Spline shaft Flange Others Spec. requirements for weight/dimensions	Rotary-lift combinations								
 Pivot shaft Hollow shaft Spline shaft Flange Others Others Spec. requirements for weight/dimensions (Please include sketch or drawing) 	Minimum lifting force [N]			Minin	num pulling f	orce [N]			
 Pivot shaft Hollow shaft Spline shaft Flange Others Others Spec. requirements for weight/dimensions (Please include sketch or drawing) Rotary-lift combinations 	Max. radial load on piston rod [N]			Max.	stroke [mm]				
Pivot shaft Hollow shaft Spline shaft Flange Others Image: Control of the state	Lifting/Stroke speed [mm/sec]			Mar. 1	_ift/Stroke wor	king proces	ro [bar]		

Place, Date

Signature